

Lecture 5

Finite State Machines

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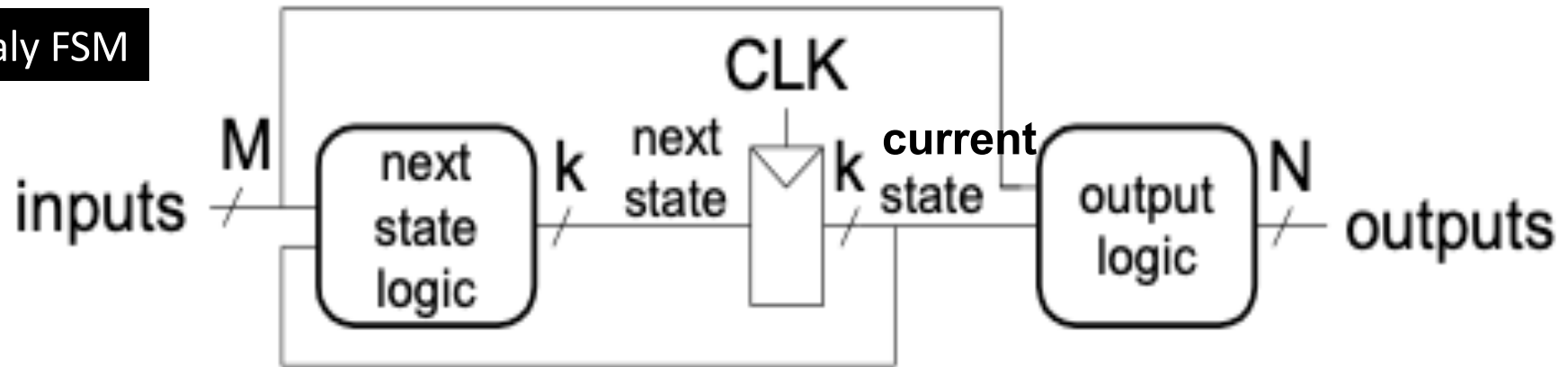
Lecture Objectives

- ◆ To learn how to **analyse** a state machine
- ◆ To learn how to **design** a state machine to meet specific objectives
- ◆ Learn how to specify a FSM in SystemVerilog
- ◆ How to combine a FSM with a counter to control state transition

Synchronous State Machines

◆ Synchronous State Machine (also called Finite State Machine FSM)

Mealy FSM



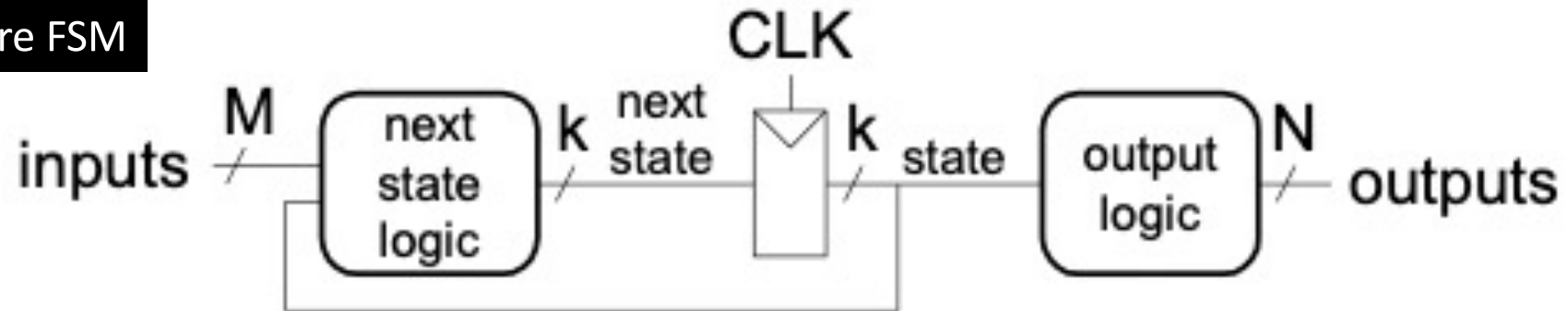
- The **current state** is defined by the register contents
- Register has k flipflops $\Rightarrow 2^k$ possible states
- The state only ever changes on CLOCK \uparrow
 - We stay in a state for an exact number of CLOCK cycles
- The state is the only memory of the past
- Output can depend on both current state and current input – **Mealy FSM**

Rules:

- ❑ Never mess around with the clock signal
- ❑ Always initialise the FSM to a known initial state on reset or power ON.

Simple FSM – Moore FSM

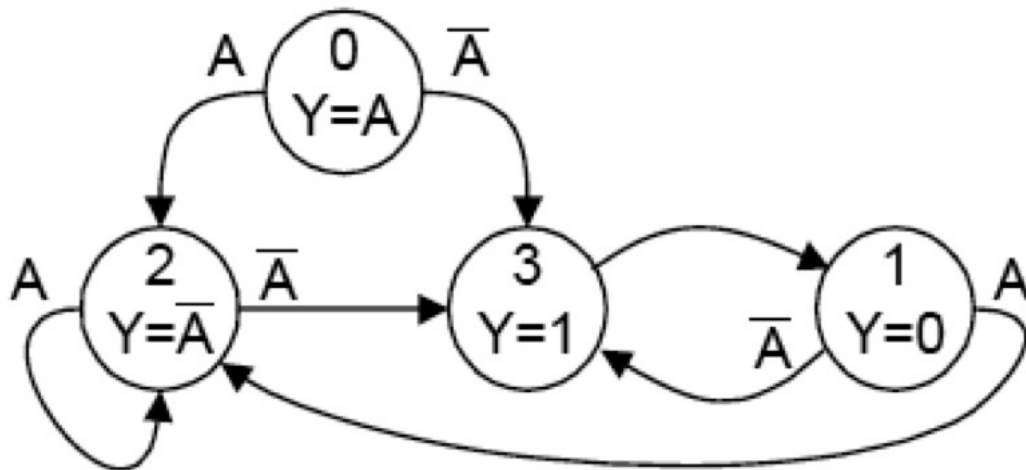
Moore FSM



- ◆ Three parts:
 - ❖ **State registers**
 - ❖ **Next state logic**
 - ❖ **Output logic**
- ◆ **Moore FSM** – special case of Mealy FSM, output depends only on current state

Drawing the State Diagram

- ◆ Split state table into two parts: next state table and output table



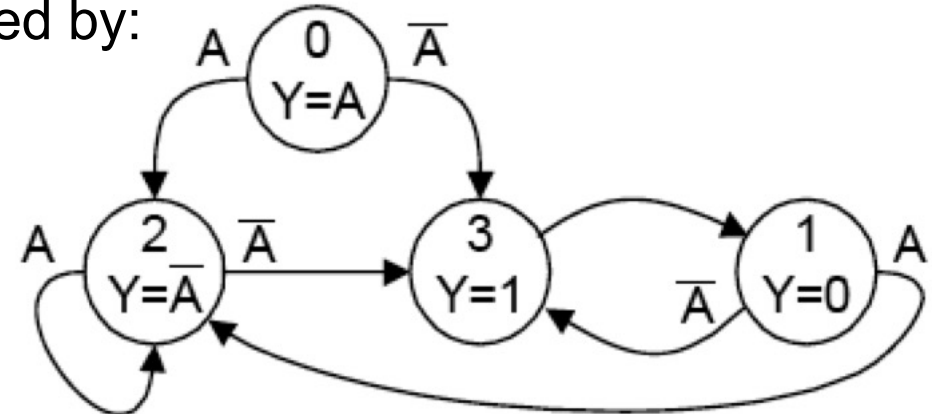
		NS1,NS0/Y		<u>Next State: NS1:0</u>		
		A=0	A=1	S1:0	A=0	A=1
S1,S0						
00		11/0	10/1	0	3	2
01		11/0	10/0	1	3	2
10		11/1	10/0	2	3	2
11		01/1	01/1	3	1	1

- ◆ Transition arrows are marked with Boolean expressions saying when they occur
 - Every input combination has exactly one destination.
 - Unlabelled arrows denote unconditional transitions
- ◆ Output Signals: Boolean expressions within each state

		<u>Output Signal: /Y</u>		
		A=0	A=1	
S1:0				
0		/0	/1	Y=A
1		/0	/0	Y=0
2		/1	/0	Y=!A
3		/1	/1	Y=1

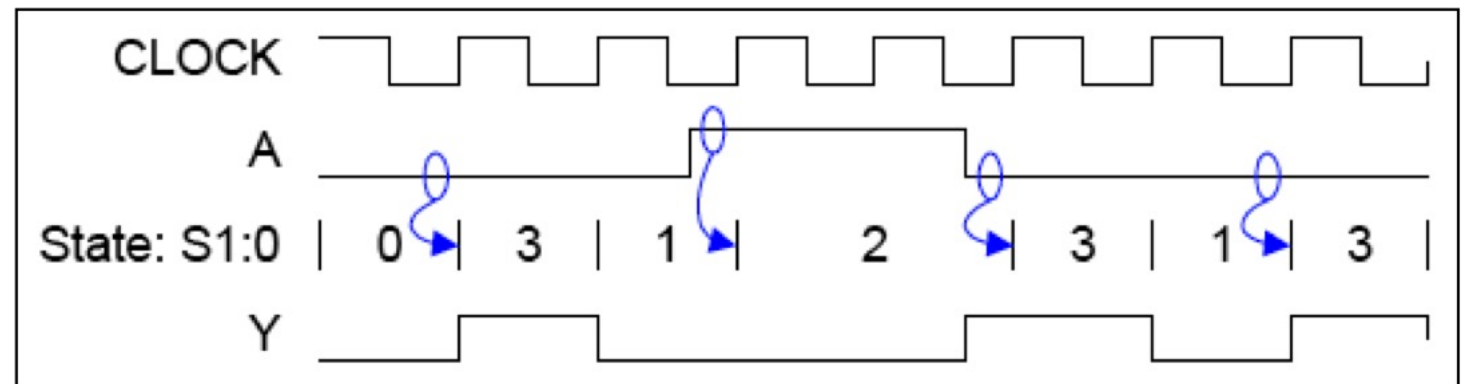
Timing Diagram

- ◆ State machine behaviour is entirely determined by:
 - The initial state
 - The input signal waveforms



- ◆ **State Sequence:**

- *Determine this first.* Next state depends on input values just before CLOCK



- ◆ **Output Signals:**

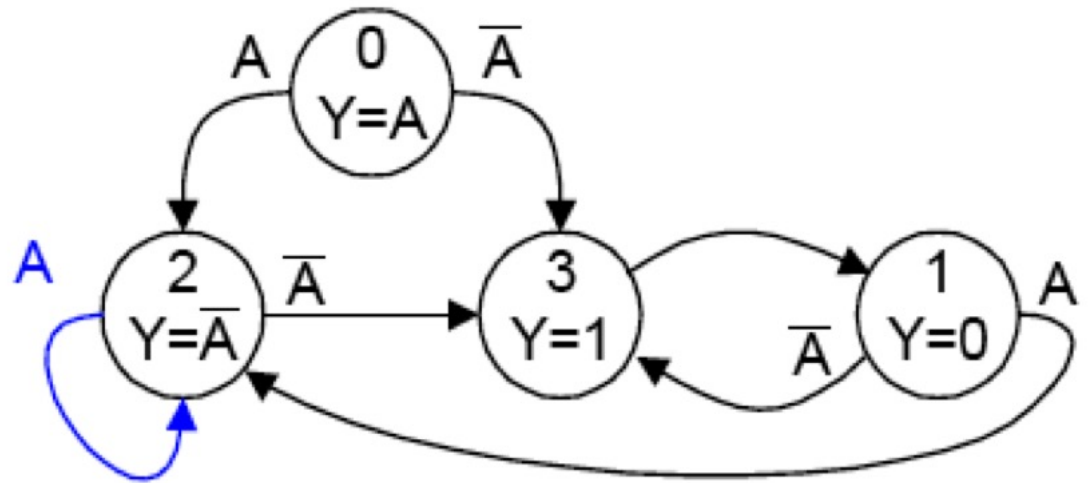
Defined by Boolean expressions within each state.

If all the expressions are constant 0 or 1 then outputs only ever change on clock . (**Moore machine**)

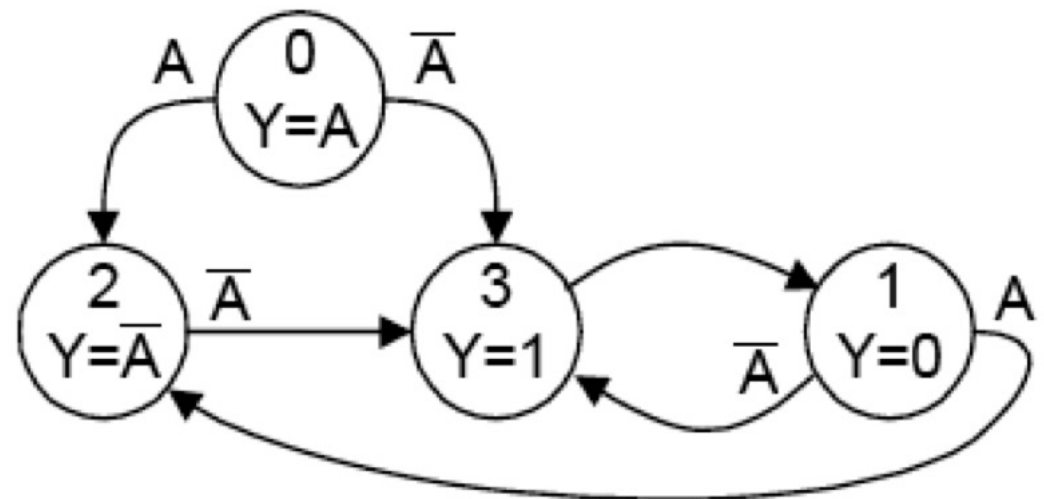
If any expressions involve the inputs (e.g. $Y=A$) then it is possible for the outputs to change in the middle of a state. (**Mealy machine**)

Self-Transitions

- ◆ We can omit transitions from a state to itself
 - Aim: to save clutter on the diagram



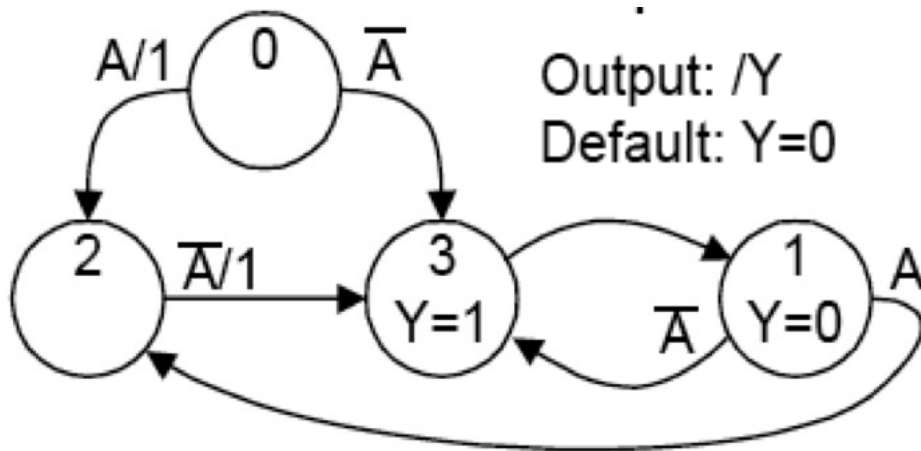
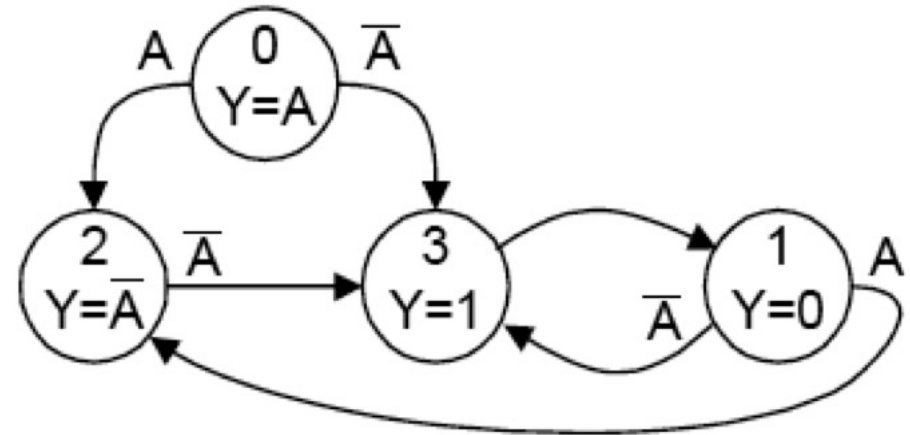
- ◆ The state machine remains in its current state if none of the transition-arrow conditions are satisfied
 - From state 2, we go to state 3 if \bar{A} occurs, otherwise we remain in state 2



Output Expressions on Arrows

- ◆ It may make the diagram clearer to put output expressions on the arrows instead of within the state circles:

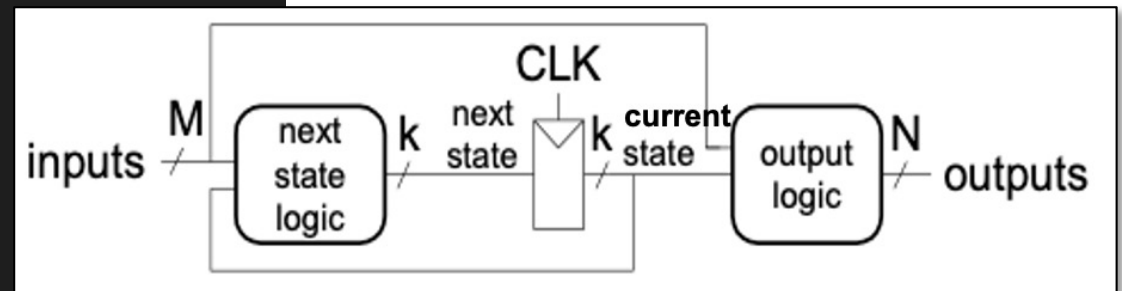
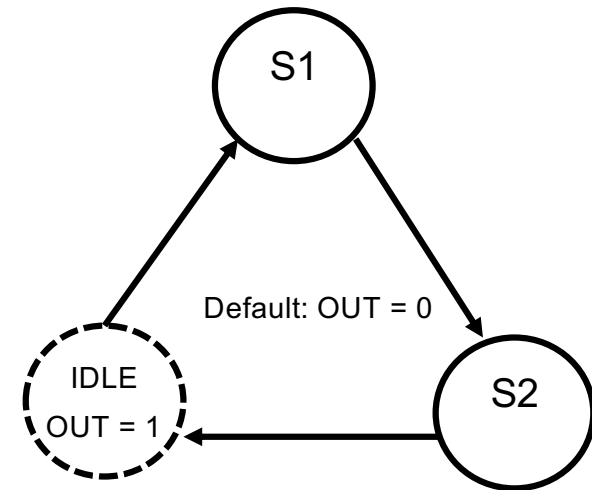
- Useful if the same Boolean expression determines both the **next state** and the **output signals**
- For each state, the output specification must be **either** inside the circle **or else** on **every** emitted arrow
- If self transitions are omitted, we must declare default values for the outputs



- Outputs written on an arrow apply to the state **emitting** the arrow.
- Outputs still apply for the entire time spent in a state
- This does not affect the Moore/Mealy distinction
- This is a notation change only

Example 1: Divide by 3 FSM (Moore)

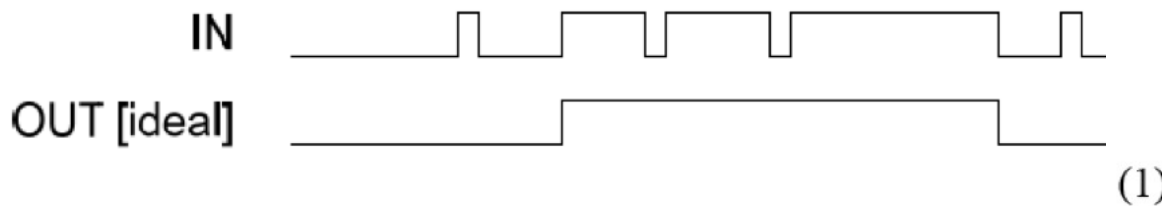
```
1 module div3FSM (  
2     input  logic clk, // clock signal  
3     input  logic rst, // asynchronous reset  
4     output logic out  // goes high 1 cycle every 3 clk cycles  
5 );  
6  
7 // Define our states  
8 typedef enum {IDLE, S1, S2} my_state;  
9 my_state current_state, next_state;  
10  
11 // state registers  
12 always_ff @(posedge clk, posedge rst)  
13     if (rst)    current_state <= IDLE;  
14     else      current_state <= next_state;  
15  
16 // next state logic  
17 always_comb  
18     case (current_state)  
19         IDLE:    next_state = S1;  
20         S1:     next_state = S2;  
21         S2:     next_state = IDLE;  
22         default: next_state = IDLE;  
23     endcase  
24  
25 // output logic  
26 assign out = (current_state == IDLE);  
27 endmodule
```



Example 2: Design a Noise Pulse Eliminator (1)

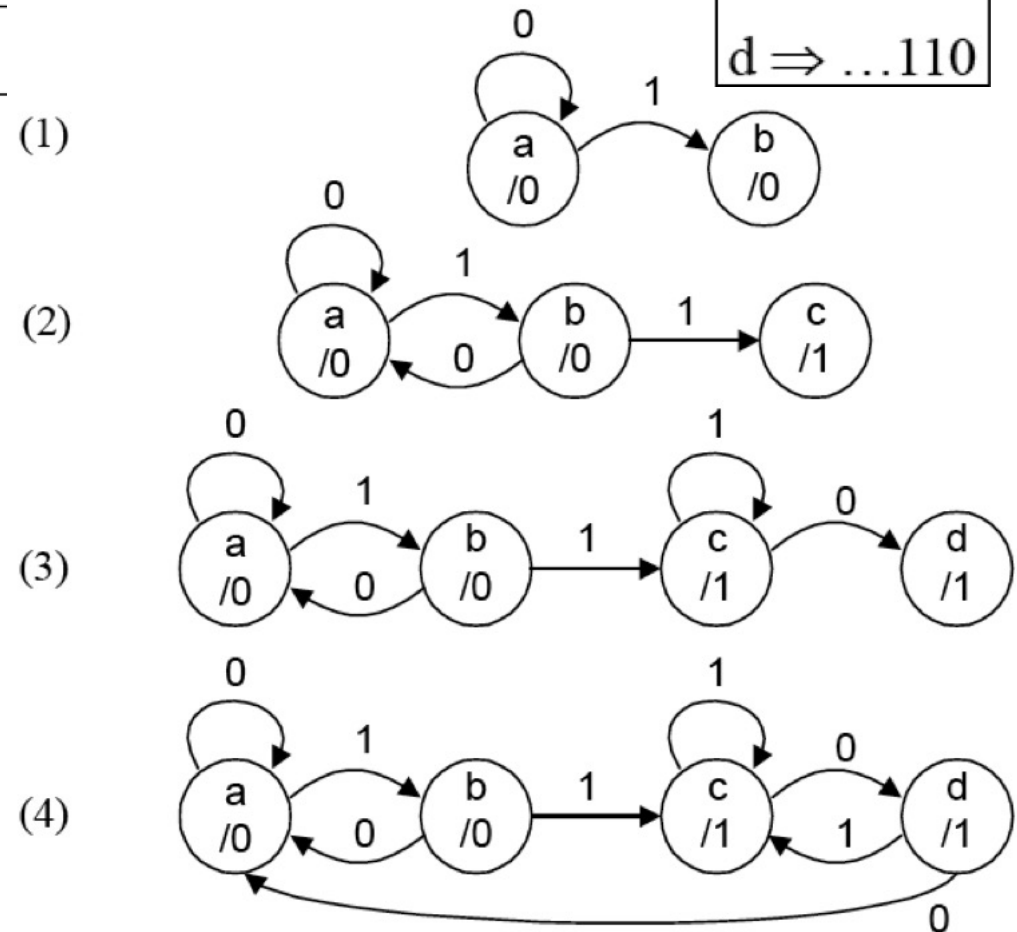
◆ **Design Problem:** Noise elimination circuit

- We want to remove pulses that last only one clock cycle



a	⇒ ...00
b	⇒ ...001
c	⇒ ...11
d	⇒ ...110

- ◆ Use letters a,b,... to label states; we choose numbers later.
- ◆ Decide what action to take in each state for each of the possible input conditions.
- ◆ Use a Moore machine (i.e. output is constant in each state). Easier to design but needs more states & adds output delay.



Design a Noise Pulse Eliminator (2)

1. If IN goes high for two (or more) clock cycles then OUT must go high, whereas if it goes high for only one clock cycle then OUT stays low. It follows that the two histories “IN low for ages” and “IN low for ages then high for one clock” are different because if IN is high for the next clock we need different outputs. Hence we need to introduce state b.
2. If IN goes high for one clock and then goes low again, we can forget it ever changed at all. This glitch on IN will not affect any of our future actions and so we can just return to state a.
If on the other hand we are in state b and IN stays high for a second clock cycle, then the output must change. It follows that we need a new state, c.
3. The need for state d is exactly the same as for state b earlier. We reach state d at the end of an output pulse when IN has returned low for one clock cycle. We don't change OUT yet because it might be a false alarm.
4. If we are in state d and IN remains low for a second clock cycle, then it really is the end of the pulse and OUT must go low. We can forget the pulse ever existed and just return to state a.

Each state represents a particular history that we need to distinguish from the others:

state **a**: IN=0 for >1 clock

state **b**: IN=1 for 1 clock

state **c**: IN=1 for >1 clock

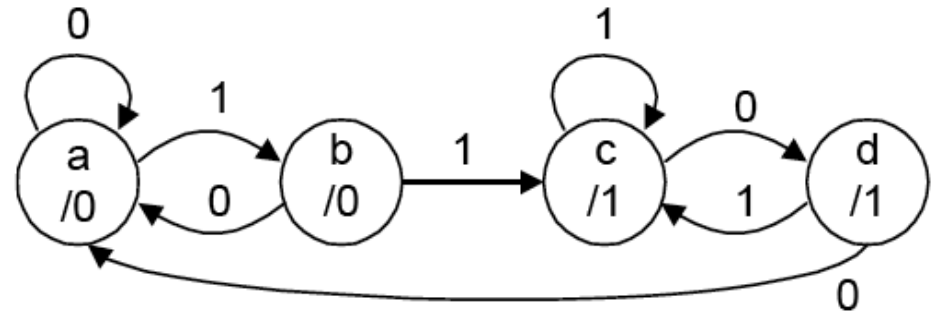
state **d**: IN=0 for 1 clock

Eliminator design in SystemVerilog

```
module eliminator (  
    input  logic clk, // clock signal  
    input  logic rst, // asynchronous reset  
    input  logic in,  // input signal  
    output logic out  // output signal  
);  
  
// Define our states  
typedef enum {S_A, S_B, S_C, S_D} my_state;  
my_state current_state, next_state;
```

Declarations

```
// next state logic  
always_comb  
    case (current_state)  
        S_A:    if (in==1'b1) next_state = S_B;  
                else        next_state = current_state;  
        S_B:    if (in==1'b1) next_state = S_C;  
                else        next_state = S_A;  
        S_C:    if (in==1'b0) next_state = S_D;  
                else        next_state = current_state;  
        S_D:    if (in==1'b1) next_state = S_C;  
                else        next_state = S_A;  
        default: next_state = S_A;  
    endcase
```

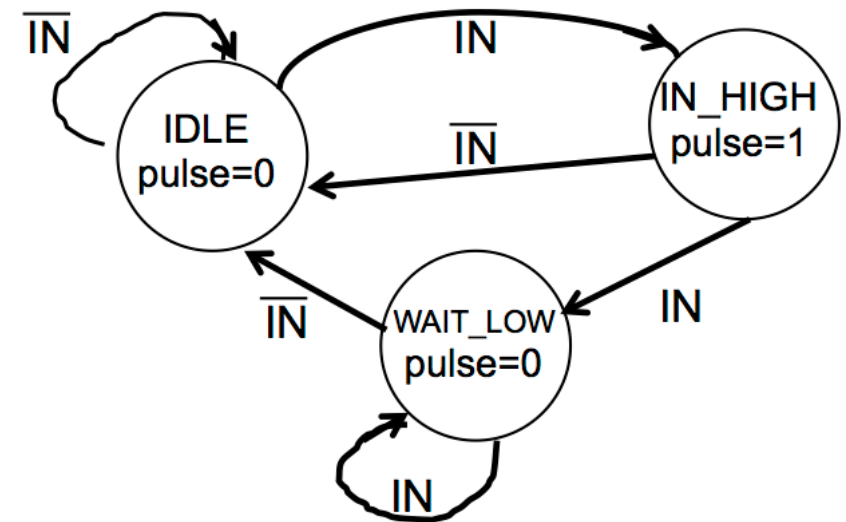
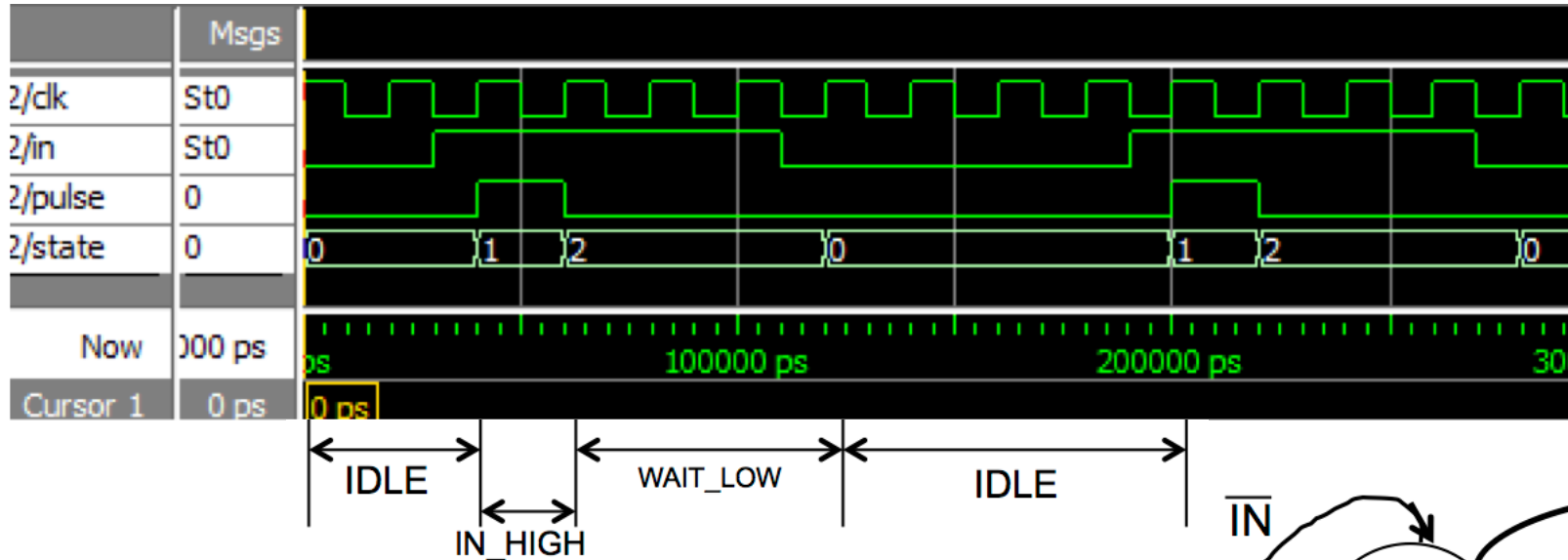


```
// state transition  
always_ff @(posedge clk)  
    if (rst)    current_state <= S_A;  
    else       current_state <= next_state;
```

```
// output logic  
always_comb  
    case (current_state)  
        S_A:    out = 1'b0;  
        S_B:    out = 1'b0;  
        S_C:    out = 1'b1;  
        S_D:    out = 1'b1;  
        default: out = 1'b0;  
    endcase
```

Example 3 – A pulse generator

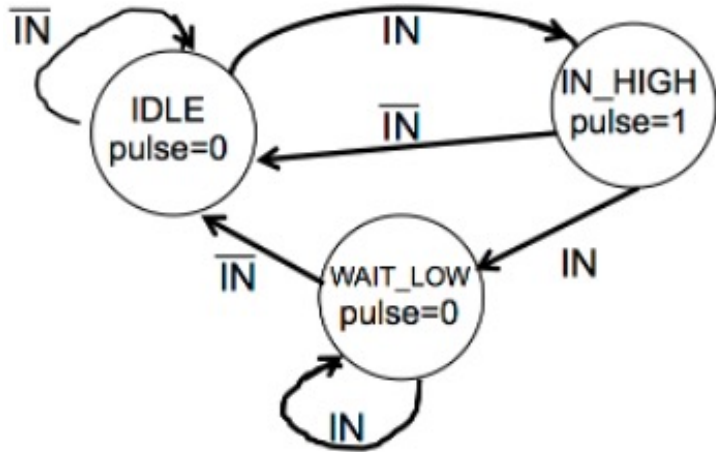
- Design a module `pulse_gen.v` which does the following: on each positive edge of the input signal **IN**, it generates a pulse lasting for one period of the input **clock**.



- Needs THREE states (not two).

Pulse Generator in SystemVerilog

- ◆ Design a module `pulse_gen.v` which does the following: on each positive edge of the input signal **IN**, it generates a pulse lasting for one period of the input **clk**.



```
// next state logic
always_comb
    case (current_state)
        IDLE:      if (in==1'b1)  next_state = IN_HIGH;
                  else           next_state = current_state;
        IN_HIGH:  if (in==1'b1)  next_state = WAIT_LOW;
                  else           next_state = IDLE;
        WAIT_LOW: if (in==1'b0)  next_state = IDLE;
                  else           next_state = current_state;
        default:  next_state = IDLE;
    endcase
```

```
module pulse_gen (
    input  logic clk, // clock signal
    input  logic rst, // asynchronous reset
    input  logic in,  // input trigger signal
    output logic pulse // output pulse signal
);

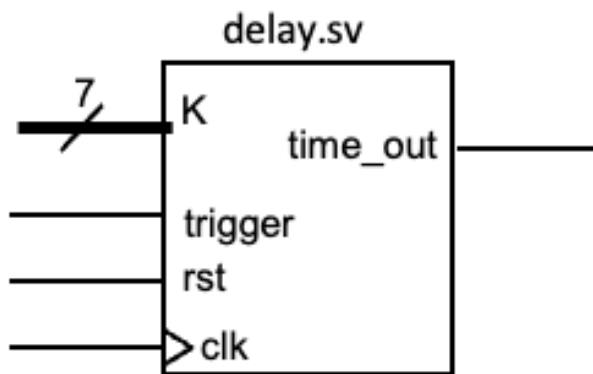
// Define our states
typedef enum {IDLE, IN_HIGH, WAIT_LOW} my_state;
my_state current_state, next_state;

// state transition
always_ff @(posedge clk)
    if (rst)    current_state <= IDLE;
    else       current_state <= next_state;
```

```
// output logic
always_comb
    case (current_state)
        IDLE:      pulse = 1'b0;
        IN_HIGH:   pulse = 1'b1;
        WAIT_LOW:  pulse = 1'b0;
        default:   pulse = 1'b0;
    endcase
```

Example 4: delay module (1)

- ◆ Here is a very useful module that combines a FSM with a counter.
- ◆ It detects the rising edge on trigger, then wait (delay) for n clk cycles before producing a 1-cycle pulse on time_out.
- ◆ The external port interface for this module is shown below. We assume that n is a 7-bit number, or a maximum of 127 sysclk cycles delay.

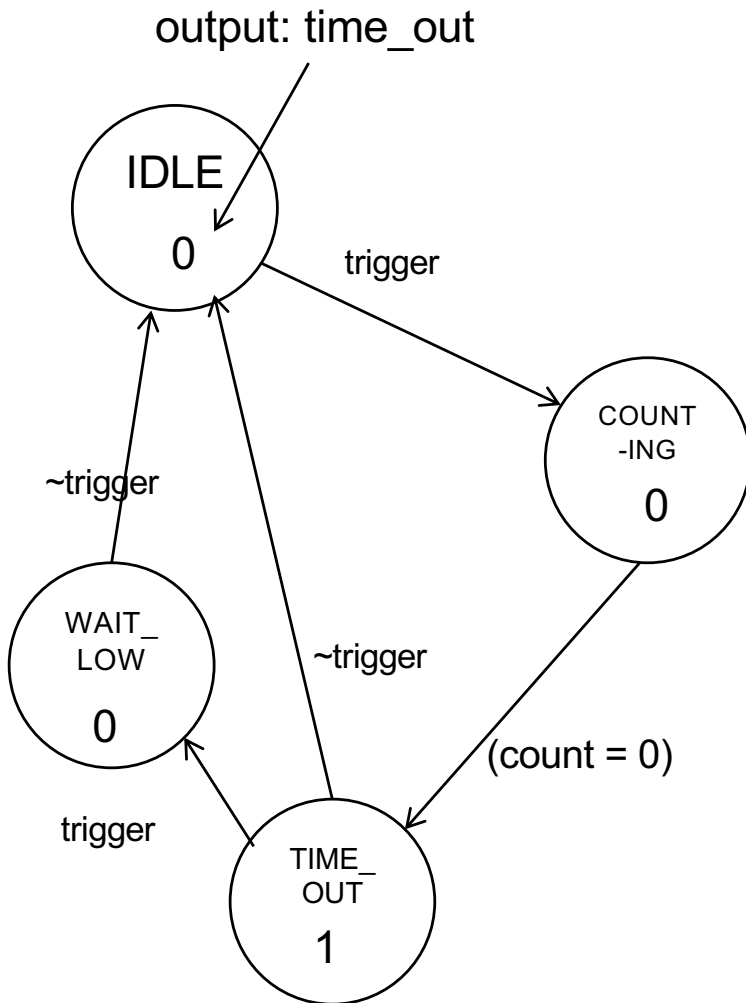


```
module delay #(
    parameter WIDTH = 7    // no of bits in delay counter
)()
    input  logic          clk,      // clock signal
    input  logic          rst,      // reset signal
    input  logic          trigger,  // trigger input signal
    input  logic [WIDTH-1:0] k,    // no of clock cycle delay
    output logic          time_out  // output pulse signal
);

// Declare counter
logic [WIDTH-1:0] count = {WIDTH{1'b0}}; // internal counter

// Define our states
typedef enum {IDLE, COUNTING, TIME_OUT, WAIT_LOW} my_state;
my_state current_state, next_state;
```

Example 4: delay module (2)



```
// next state logic
always_comb
case (current_state)
  IDLE:      if (trigger==1'b1) next_state = COUNTING;
             else next_state = current_state;
  COUNTING:  if (count=={WIDTH{1'b0}}) next_state = TIME_OUT;
             else next_state = current_state;
  TIME_OUT:  if (trigger==1'b1) next_state = WAIT_LOW;
             else next_state = IDLE;
  WAIT_LOW:  if (trigger==1'b0) next_state = IDLE;
             else next_state = current_state;
  default:  next_state = IDLE;
endcase
```

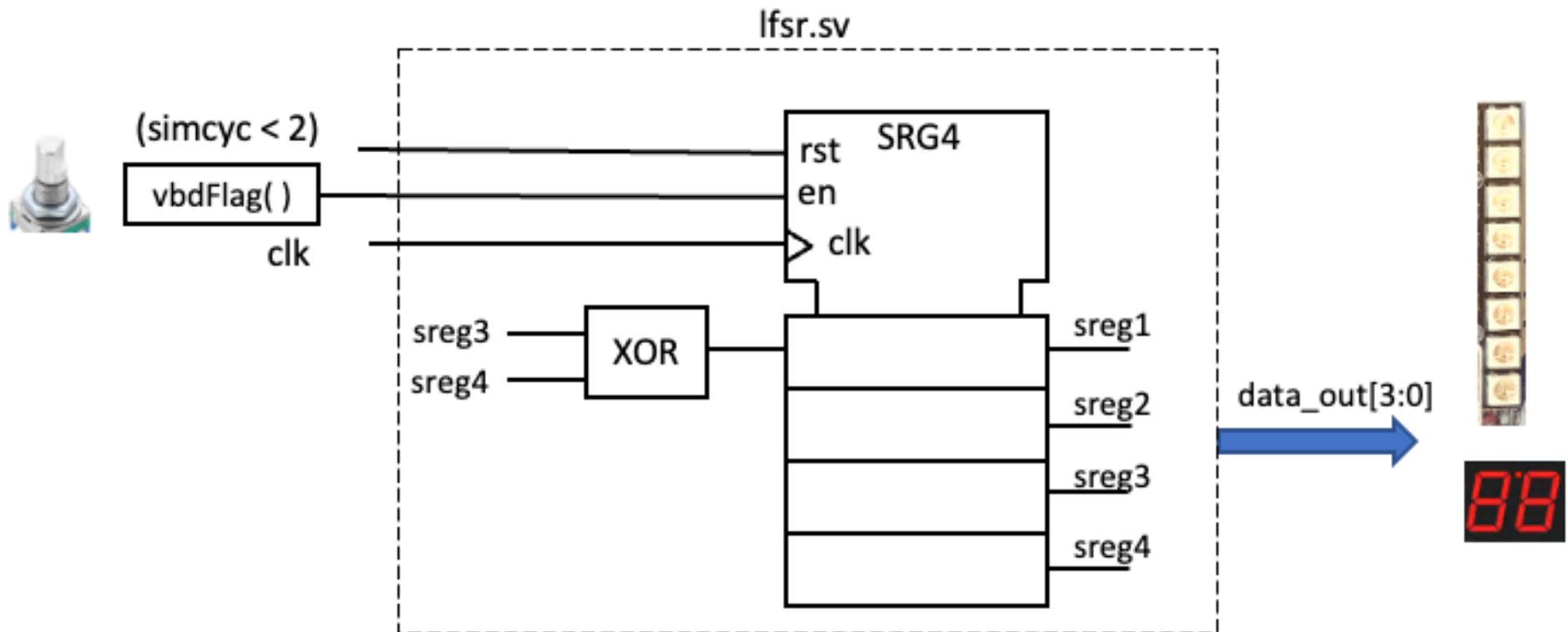
```
// output logic
always_comb
case (current_state)
  IDLE:      time_out = 1'b0;
  COUNTING:  time_out = 1'b0;
  TIME_OUT:  time_out = 1'b1;
  WAIT_LOW:  time_out = 1'b0;
  default:   time_out = 1'b0;
endcase
```

Example 4: delay module (3)

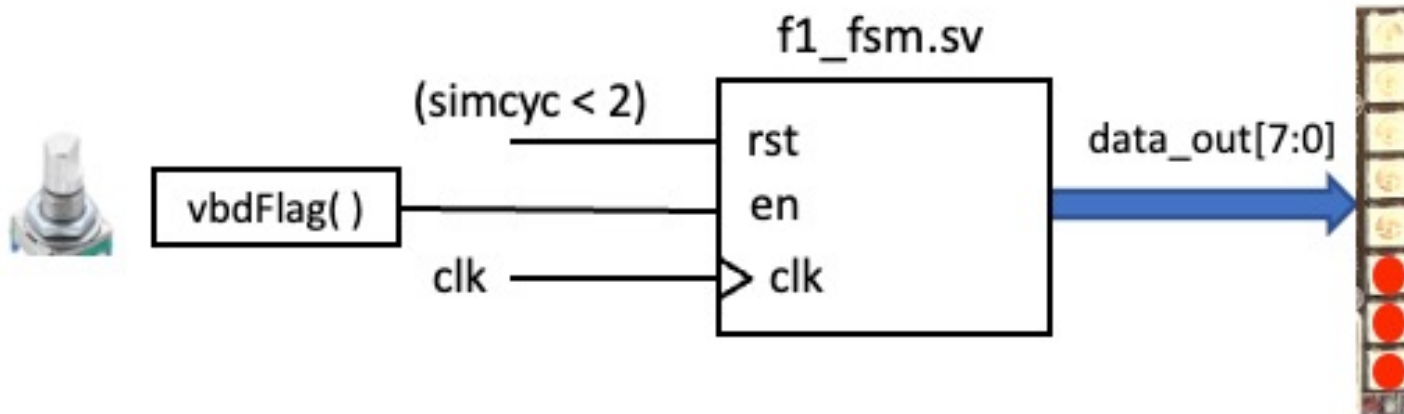
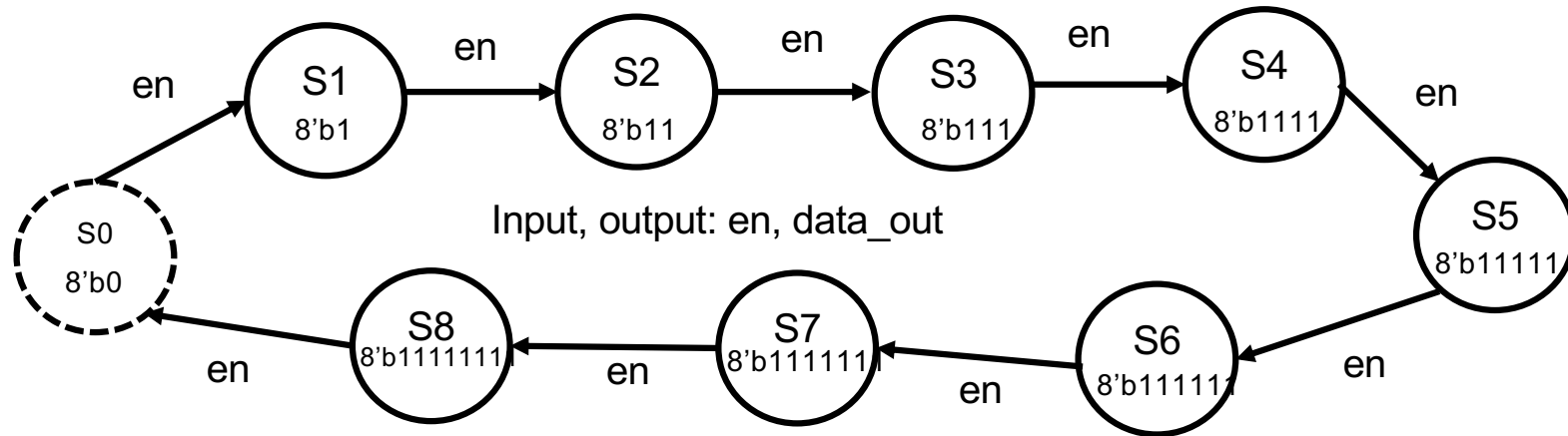
```
// counter
always_ff @(posedge clk)
    if (rst | current_state==IDLE)    count <= k - 1'b1;
    else if (current_state==COUNTING) count <= count - 1'b1;

// state transition
always_ff @(posedge clk)
    if (rst)    current_state <= IDLE;
    else       current_state <= next_state;
```

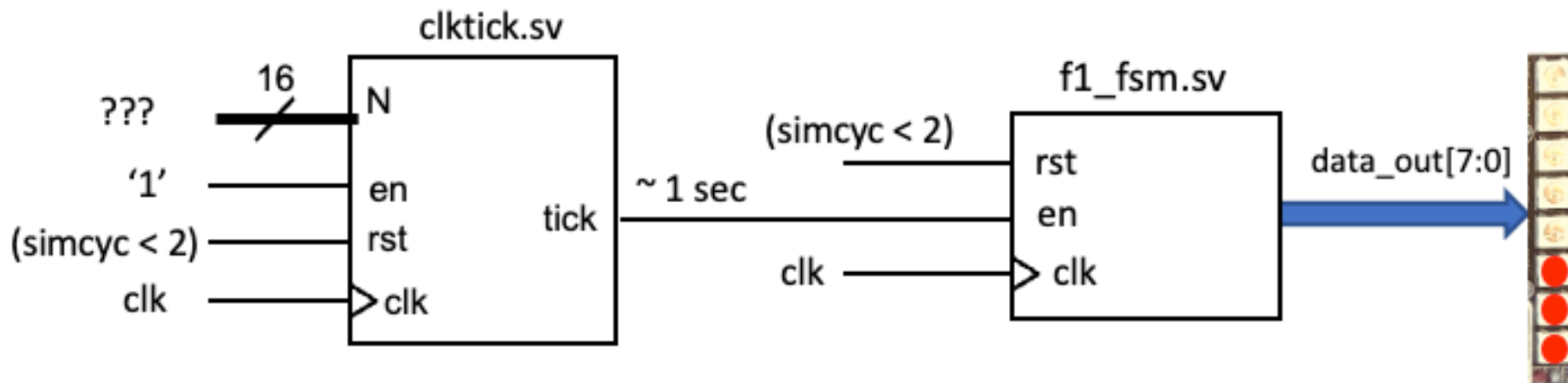
Lab 3 Task 1 – LFSR and random number generator



Lab 3 Task 2 – FSM & F1 light sequence



Lab 3 Task 3 – clktick & F1 lights



Lab 3 Task 4 – F1 starting light (optional)

